

STATS 721 (2012) FINAL EXAM SOLUTIONS:

$$\begin{aligned} 1) \ a) \quad E[X_{t+1}^2 \mid X_0, \dots, X_t, Y_0, \dots, Y_t] &= \\ &= \frac{2}{8}(X_t - 2)^2 + \frac{2}{8}(X_t - 1)^2 + \frac{2}{8}(X_t + 1)^2 + \frac{2}{8}(X_t + 2)^2 \\ &= X_t^2 + \frac{1}{4}(4 + 1 + 1 + 4) \\ &= X_t^2 + \frac{5}{2}. \end{aligned}$$

Similarly,

$$E[Y_{t+1}^2 \mid X_0, \dots, X_t, Y_0, \dots, Y_t] = Y_t^2 + \frac{5}{2}.$$

So

$$E[R_{t+1}^2 \mid \dots] = R_t^2 + 5.$$

$$\begin{aligned} E[M_{t+1} \mid \dots] &= R_t^2 + 5 - \beta(t+1) \\ &= M_t + 5 - \beta \end{aligned}$$

and thus  $\beta = 5$  is the only possible value.

b) Minimum value is  $\begin{cases} 0, & \text{if } t \text{ is even (return to start)} \\ 5, & \text{if } t \text{ is odd (one move away from start)} \end{cases}$

Maximum is  $5t^2$  (all  $t$  moves in the same direction).

Expected value is (by the martingale property)

$$E[R_t^2] = E[M_t + 5t] = E[M_0] + 5t = 5t.$$

c) We know when to stop: the event  $\{T=t\}$  is determined by  $(X_0, \dots, X_t, Y_0, \dots, Y_t)$ .

d) The process will stop whenever there are  $\lceil \frac{2r}{\sqrt{5}} \rceil$  consecutive moves towards the boundary circle.

The probability that this happens in any  $m$  consecutive moves is  $(\frac{1}{8})^m > 0$ . So  $T/m$  is dominated by a

geometric random variable.

e) Optional stopping theorem.

Let  $M_t' = M_{T \wedge t}$ . We need to check

$$E[|M_{t+1}' - M_t'|] \text{ bounded;}$$

this holds because  $|M_{t+1}' - M_t'| = |R_{T \wedge (t+1)}^2 - R_{T \wedge t}^2 - 5|$

$$(2r^2 + 5) < \infty.$$

(Also  $E[T] < \infty$  as noted in (d)).

O.S.T. gives us

$$E[M_T^*] = E[M_T'] = E[M_0'] = 0.$$

$$\therefore E[R_T^2] - 5 \cdot E[T] = 0$$

$$\text{so } E[T] = \frac{E[R_T^2]}{5} \geq \frac{r^2}{5}.$$

~~$$3) \mu_k = 1 + \frac{3}{4} \mu_{k+1} + \frac{1}{4} \mu_{k+2}$$~~

3) ~~of~~ The generating-function calculation in (c), (d) are not valid here because they rely on translation-invariance.

For (c), the probability of never reaching state 1 is the same (d); adding a boundary beyond state 1 cannot change this.

For (d), let  $p_k = P(\text{reach state 0})$  starting from  $k$ .

Then  $p_0 = 1$ , ~~and~~  $p_{100} = 0$ , and

$$p_k = \frac{3}{4} p_{k+1} + \frac{1}{4} p_{k-1}.$$

Solve this difference equation.

The probability we want is  $1 - \left(\frac{3}{4} p_1 + \frac{1}{4} p_{-1}\right)$ .