# Semi-parametric efficiency bounds for regression models under choice-based sampling 

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Summary. We extend the Bickel-Klaassen-Ritov-Wellner theory of semi-parametric efficiency bounds to the case of sampling from several populations, and discuss the form of the efficient score and efficient influence function in this situation. The theory is applied to obtain an information bound for estimates of parameters in general regression models under case-control sampling. The variances of the semi-parametric estimates of Scott and Wild (1991, 1997, 2001) are compared to the bound and the estimates are found to be fully efficient.

Key words: Semi-parametric efficiency, choice-based sampling, case-control study, tangent space, influence function, efficient score, information bound.

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## 1. INTRODUCTION

In this paper, we present a semi-parametric efficiency bound for the parameters of regression models fitted to data obtained by choice-based sampling. Previous authors have addressed this question using the theory of semi-parametric efficiency developed by Bickel et al. (1993). This theory assumes an i.i.d. sample, so various ingenious devices have been used to apply it to the case of choice-based sampling. For example, Breslow, Robins and Wellner (2000) consider case-control sampling, assuming that the data are generated by Bernoulli sampling, where either a case or control is selected by a randomisation device with known selection probabilities, and the covariates of the resulting case or control are measured. The randomisation at the first stage means that the i.i.d. theory can be applied.

Breslow, McNeney and Wellner (2003) apply the missing value theory of Robins, Rotnitzky and Zhao (1994) and Robins, Hsieh and Newey (1995) to render the i.i.d. theory applicable. Here, individuals in the population are selected at random and their status (case or control) is determined. Then with a probability depending on their status, the covariates are measured or not. The unobserved covariates are treated as missing data.

We adopt a more direct approach. First, the Bickel-Klaassen-Ritov-Wellner theory is extended to the case of sampling from several populations. Then information bounds for the regression parameters are derived assuming that separate prospective samples are taken from the case and control populations.

The minor modifications to the standard theory required for the multi-sample efficiency bounds are sketched in Section 2. This theory is then applied to case control sampling and an information bound derived in Section 3. The approach to estimation based on profile likelihood outlined by Scott and Wild (1991, 1997, 2001) is considered in Section 4 and found to be fully efficient.

## 2. INFORMATION BOUNDS FOR THE MULTI-SAMPLE CASE

### 2.1 Preliminaries

We first consider a direct sum of Hilbert spaces that will play an important role in the derivation of the information bound. Suppose $\mathcal{H}_{1}, \ldots, \mathcal{H}_{J}$ are Hilbert spaces with inner product $(\cdot, \cdot)_{j}$ on $\mathcal{H}_{j}$, and that $w_{1}, \ldots, w_{J}$ are positive constants. Then we may define an inner product $(\cdot, \cdot)$ on the direct sum $\mathcal{H}=\mathcal{H}_{1} \times \cdots \times \mathcal{H}_{J}$ by

$$
\begin{equation*}
\left(\left(g_{1}, \ldots, g_{J}\right),\left(h_{1}, \ldots, h_{J}\right)\right)=\sum_{j=1}^{J} w_{j}\left(g_{j}, h_{j}\right)_{j} \tag{1}
\end{equation*}
$$

Specifically, the spaces we will consider will be of the form $L_{2, k}\left(P_{1}\right), \ldots, L_{2, k}\left(P_{J}\right)$, where $L_{2, k}\left(P_{j}\right)$ is the set of all $k$-dimensional functions that are square integrable with respect to a probability measure $P_{j}$. The inner product on $L_{2, k}\left(P_{j}\right)$ is

$$
\begin{align*}
\left(\left(a_{1}, \ldots, a_{J}\right),\left(b_{1}, \ldots, b_{J}\right)\right) & =\sum_{l=1}^{k} \int a_{l}(x) b_{l}(x) d P_{j}(x)  \tag{2}\\
& =\sum_{l=1}^{k}\left(a_{l}, b_{l}\right)_{l j} \tag{3}
\end{align*}
$$

say. The following result will be useful:
Theorem 1 Let $\mathcal{H}=L_{2, k}\left(P_{1}\right) \times \cdots \times L_{2, k}\left(P_{J}\right)$, and for $h=\left(h_{1}, \ldots, h_{J}\right) \in \mathcal{H}$, let $[h]$ denote the subspace of all functions of the form $\left(A h_{1}, \ldots, A h_{J}\right)$ for some constant $k \times k$ matrix $A$. If $g=\left(g_{1}, \ldots, g_{J}\right) \in \mathcal{H}$, then $g \perp[h]$ if and only if

$$
\sum_{j=1}^{J} w_{j} E_{j}\left(g_{j} h_{j}^{T}\right)=0
$$

where $E_{j}$ denotes expectation with respect to $P_{j}$.

Proof. Let $A=\left(a_{i j}\right)$ be an arbitrary $k \times k$ matrix. Then

$$
\begin{aligned}
(g, A h) & =\sum_{j=1}^{J} w_{j}\left(g_{j}, A h_{j}\right)_{j} \\
& =\sum_{j=1}^{J} w_{j} \sum_{i=1}^{k}\left(g_{i j}, \sum_{l=1}^{k} a_{i l} h_{l j}\right)_{l j} \\
& =\sum_{i=1}^{k} \sum_{l=1}^{k} a_{i l} \sum_{j=1}^{J} w_{j}\left(g_{i j}, h_{l j}\right)_{l j} \\
& =\sum_{i=1}^{k} \sum_{l=1}^{k} a_{i l}\left\{\sum_{j=1}^{J} w_{j} E_{j}\left(g_{j} h_{j}^{T}\right)_{i l}\right\}
\end{aligned}
$$

so that $g \perp[h]$ if and only if $\sum_{j=1}^{J} w_{j} E_{j}\left(g_{j} h_{j}^{T}\right)=0$.

### 2.2 The multi-sample model

Suppose for $j=1, \ldots, J$ we observe independent random variables $X_{i j}, i=1, \ldots, n_{j}$, which for fixed $j$ are identically distributed with density $p_{0 j}$. The densities $p_{0 j}$ are members of classes of densities $\mathcal{P}_{j}$ of the form

$$
\mathcal{P}_{j}=\left\{p_{j}(x ; \beta, \eta): \beta \in B, \eta \in N\right\}
$$

where $B$ is a finite dimensional set and $N$ is infinite dimensional. We regard $\mathcal{P}=\mathcal{P}_{1} \times \cdots \times \mathcal{P}_{J}$ as a model for our data. We will need to consider parametric submodels of $\mathcal{P}$; these are models of the form $\mathcal{Q}=\mathcal{Q}_{1} \times \cdots \times \mathcal{Q}_{J}$ where

$$
\mathcal{Q}_{j}=\left\{p_{j}(x ; \beta, \gamma): \beta \in B_{0}, \gamma \in \Gamma\right\}
$$

$B_{0}$ is a subset of $B$ and $\Gamma$ has finite dimension.
We suppose that the family of densities $\mathcal{P}$ is regular, in the sense that for every finite-dimensional subfamily $\mathcal{Q}$ with $p_{j 0} \in \mathcal{Q}_{j}$, the mapping from $B_{0} \times \Gamma$ to $L_{2}\left(P_{0 j}\right)$ defined by

$$
(\beta, \gamma) \rightarrow 2\left(\sqrt{\frac{p_{j}(\cdot, \beta, \gamma)}{p_{0 j}(\cdot)}}-1\right) I_{\left\{p_{0 j}>0\right\}}
$$

is Fréchet differentiable for every $p_{j}$ in $\mathcal{Q}_{j}, j=1, \ldots, J$. This is sufficient to guarantee the existence of a square-integrable score function; see Bickel et al. (1993, Section 2.1) for details.

### 2.3 Tangent spaces

The tangent space $\mathcal{T}$ of the family $\mathcal{P}$ is the subspace of $\mathcal{H}=L_{2, k}\left(P_{1}\right) \times \cdots \times L_{2, k}\left(P_{J}\right)$ formed by taking the closure of the linear space of all elements of the form $\left(A S_{1}, \ldots, A S_{J}\right)$, where $A$ is a constant
matrix with $k$ rows and $S=\left(S_{1}, \ldots, S_{J}\right)$ is the score function of a finite dimensional submodel of $\mathcal{P}$. We can also define the tangent spaces $\mathcal{T}_{\beta}$ and $\mathcal{T}_{\eta}$ corresponding to the families $\mathcal{P}_{\beta}$ and $\mathcal{P}_{\eta}$ defined by

$$
\mathcal{P}_{\beta}=\left\{\left(p_{1}\left(\cdot, \beta, \eta_{0}\right), \ldots, p_{J}\left(\cdot, \beta, \eta_{0}\right)\right): \beta \in B\right\}
$$

and

$$
\mathcal{P}_{\eta}=\left\{\left(p_{1}\left(\cdot, \beta_{0}, \eta\right), \ldots, p_{J}\left(\cdot, \beta_{0}, \eta\right)\right): \eta \in N\right\}
$$

The space $\mathcal{T}_{\eta}$ is called the nuisance tangent space. We will require that $\mathcal{T}=\mathcal{T}_{\beta}+\mathcal{T}_{\eta}$; this will have to be established for the examples we consider.

### 2.4 RAL estimators and influence functions.

Let $n=\sum_{j=1}^{J} n_{j}$ and suppose that for each $j, n_{j} / n \rightarrow w_{j}$. An estimator $\hat{\beta}_{n}$ based on our data $X_{i j}$ is asymptotically linear if

$$
\begin{equation*}
\sqrt{n}\left(\hat{\beta}_{n}-\beta_{0}\right)=n^{-1 / 2} \sum_{j=1}^{J} \sum_{i=1}^{n_{j}} \sqrt{w_{j}} \psi_{j}\left(X_{i j}\right)+o_{p}(1) . \tag{4}
\end{equation*}
$$

where $\psi=\left(\psi_{1}, \ldots, \psi_{J}\right)$ is in $\mathcal{H}$. The function $\psi$ is called the influence function of the estimator.
As in the i.i.d. case, for a finite dimensional family we will say that an estimate is regular if $\sqrt{n}\left(\hat{\beta}_{n}-\beta_{n}\right)$ converges to the same distribution whenever $\sqrt{n}\left(\left(\beta_{n}, \gamma_{n}\right)-\left(\beta_{0}, \gamma_{0}\right)\right)$ converges to a constant. Here the convergence is under the assumption that for a given $n$, the data on which $\hat{\beta}_{n}$ is based are distributed as $p_{j}\left(\cdot, \beta_{n}, \gamma_{n}\right)$.

An estimate is regular for an infinite dimensional family if it is regular for every finite-dimensional subfamily. We shall be concerned with estimates that are both regular and asymptotically linear, or RAL.

A key part of the theory of efficiency bounds in the i.i.d. case is a theorem that relates the influence function of a RAL estimate to the scores. Versions of this theorem may be found for example in Bickel et al. (1993, p 39, p 65) and Newey (1990, Theorem 2.2). We now extend this theorem to the multisample case.

Theorem 2 Let $\mathcal{Q}$ be a finite-dimensional parametric family of densities with

$$
\mathcal{Q}_{j}=\left\{p_{j}(x ; \beta, \gamma): \beta \in B, \gamma \in \Gamma\right\}
$$

and score function $S=\left(S_{1}, \ldots, S_{J}\right)$, where $S_{j}=\left(S_{\beta, j}, S_{\gamma, j}\right)$. Suppose that $\hat{\beta}_{n}$ is a $R A L$ estimator with influence function $\psi$. Then

$$
\begin{equation*}
\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j} S_{\beta, j}^{T}\right)=I^{k \times k} \tag{5}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j} S_{\gamma, j}^{T}\right)=O^{k \times r} \tag{6}
\end{equation*}
$$

where $r$ is the dimension of $\Gamma$.

Proof. For brevity, we write $\theta=(\beta, \gamma)$. We assume that the densities $p_{j}$ are sufficiently well behaved so that the log-likelihood

$$
l(\theta)=\sum_{j=1}^{J} \sum_{i=1}^{n_{j}} \log p_{j}\left(x_{i j}, \theta\right)
$$

satisfies

$$
l\left(\theta_{0}+n^{-1 / 2} t\right)-l\left(\theta_{0}\right)=t^{T} \frac{\partial l}{\partial \theta}-\frac{1}{2} t^{T} I(\theta) t+o_{p}(1)
$$

where

$$
I(\theta)=\sum_{j=1}^{J} w_{j} E_{j}\left(S_{j} S_{j}^{T}\right)
$$

Then

$$
\left[\begin{array}{c}
\sqrt{n}\left(\hat{\beta}_{n}-\beta_{0}\right) \\
l\left(\theta+n^{-1 / 2} t\right)-l(\theta)
\end{array}\right]=\left[\begin{array}{c}
0 \\
-\frac{1}{2} t^{T} I(\theta) t
\end{array}\right]+\sum_{j=1}^{J} n_{j}^{-1 / 2} \sum_{i=1}^{n_{j}} w_{j}^{1 / 2}\left[\begin{array}{c}
\psi_{j}\left(x_{i j}\right) \\
t^{T} S_{j}
\end{array}\right]+o_{p}(1)
$$

which converges to

$$
N\left(\left[\begin{array}{c}
0 \\
-\frac{1}{2} t^{T} I(\theta) t
\end{array}\right],\left[\begin{array}{ll}
\Sigma_{11} & \Sigma_{12} \\
\Sigma_{21} & \Sigma_{22}
\end{array}\right]\right)
$$

where

$$
\begin{aligned}
\Sigma_{11} & =\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j} \psi_{j}^{T}\right) \\
\Sigma_{12} & =\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j} t^{T} S_{j}\right) \\
\Sigma_{21} & =\Sigma_{12}^{T} \\
\Sigma_{21} & =t^{T} I(\theta) t
\end{aligned}
$$

Hence, by standard contiguity arguments,

$$
\begin{equation*}
\sqrt{n}\left(\hat{\beta}_{n}-\beta_{n}\right) \xrightarrow{\theta_{n}=\theta_{0}+t / \sqrt{n}} N\left(\Sigma_{12}, \Sigma_{11}\right) . \tag{7}
\end{equation*}
$$

Now write $t=\left(t_{\beta}, t_{\gamma}\right)$. Since $\hat{\beta}_{n}$ is regular, $\sqrt{n}\left(\hat{\beta}_{n}-\beta_{0}-n^{-1 / 2} t_{\beta}\right)$ converges to the same limit no matter what the value of $t$ When $t=0$, the limit is $N\left(0, \Sigma_{11}\right)$ by the asymptotic linearity, so that we must have

$$
\begin{equation*}
\sqrt{n}\left(\hat{\beta}_{n}-\beta_{0}\right) \xrightarrow{\theta_{n}=\theta_{0}+t / \sqrt{n}} N\left(t_{\beta}, \Sigma_{11}\right) . \tag{8}
\end{equation*}
$$

Comparing (7) and (8), we see that $t_{\beta}=\Sigma_{12}$, or

$$
t_{\beta}=\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j} S_{\beta, j}^{T}\right) t_{\beta}+\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j} S_{\gamma, j}^{T}\right) t_{\gamma}
$$

Since this is true for all $t_{\beta}, t_{\gamma}$, we must have (5) and (6).
Our next result extends this to infinite-dimensional models. We first need the concept of the efficient influence function.

### 2.5 Efficient influence functions and the information bound.

Now we return to the case where $N$ may be infinite dimensional. For $j=1, \ldots, J$, let $S_{j, \beta}$ denote the score $\frac{\partial p_{j}(\cdot, \beta, \eta)}{\partial \beta} / p_{j}(\cdot, \beta, \eta) I_{\left\{p_{j}>0\right\}}$, and let $S_{\beta}=\left(S_{1, \beta}, \ldots, S_{J, \beta}\right)$. The efficient score is the element of $\mathcal{H}$ defined by

$$
S^{e f f}=S_{\beta}-\Pi\left(S_{\beta} \mid \mathcal{T}_{\eta}\right)=\Pi\left(S_{\beta} \mid \mathcal{T}_{\eta}^{\perp}\right)
$$

where $\Pi\left(\cdot \mid \mathcal{T}_{\eta}\right)$ denotes the orthogonal projection in $\mathcal{H}$ onto the nuisance tangent space $\mathcal{T}_{\eta}$.
Let $I_{\text {eff }}$ denote the matrix $\sum_{j=1}^{J} w_{j} E_{j}\left(S_{j}^{\text {eff }} S_{j}^{\text {eff }}{ }^{T}\right)$. The element $\left(I_{\text {eff }}^{-1} S_{1}^{\text {eff }}, \ldots, I_{\text {eff }}^{-1} S_{J}^{\text {eff }}\right)$ of $\mathcal{H}$ is called the efficient influence function and is denoted by $\psi^{e f f}$. Our next result establishes the information bound.

Theorem 3 Let $\mathcal{P}$ be as in Section 2.2 with $N$ infinite dimensional, and suppose that $\mathcal{T}=\mathcal{T}_{\beta}+\mathcal{T}_{\eta}$, and that $\hat{\beta}_{n}$ is a RAL estimate with influence function $\psi$. Then $\psi-\psi^{e f f} \perp \mathcal{T}$ and hence the matrix $n \operatorname{Var}\left(\hat{\beta}_{n}\right)-I_{\text {eff }}^{-1}$ is positive definite.

Proof. Let $h$ be the score function for a finite-dimensional submodel $\mathcal{Q}$ of $\mathcal{P}$. Since $\mathcal{T}=\mathcal{T}_{\beta}+\mathcal{T}_{\eta}$, we can write $h=h_{\beta}+h_{\gamma}$, where $h_{\beta} \in \mathcal{T}_{\beta}$ and $h_{\gamma} \in \mathcal{T}_{\eta}$. Since $\mathcal{Q}$ is finite dimensional, $h_{\gamma}$ must be the score function of a model of the form $\left\{\left(\left(p_{1}\left(\beta_{0}, \gamma\right), \ldots, p_{J}\left(\beta_{0}, \gamma\right)\right): \gamma \in \Gamma\right\}\right.$ where $\Gamma$ is finite-dimensional. In the rest of the proof we will make use of the finite dimensional model $\mathcal{Q}^{*}=\left\{\left(\left(p_{1}(\beta, \gamma), \ldots, p_{J}(\beta, \gamma)\right): \beta \in B, \gamma \in \Gamma\right\}\right.$.

We first prove that $\left(\psi-\psi^{e f f}, h_{\beta}\right)=0$. Since $h_{\beta} \in \mathcal{T}_{\beta}=\left[S_{\beta}\right]$, by Theorem 1 it is enough to prove that

$$
\begin{equation*}
\sum_{j=1}^{J} w_{j} E_{j}\left[\left(\psi_{j}-\psi_{j}^{e f f}\right) S_{j, \beta}^{T}\right]=0 \tag{9}
\end{equation*}
$$

By Theorem 2 applied to the submodel $\mathcal{Q}^{*}$, we get

$$
\begin{equation*}
\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j} S_{j, \beta}^{T}\right)=I^{k \times k} \tag{10}
\end{equation*}
$$

Also,

$$
\begin{align*}
\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j}^{e f f} S_{j, \beta}^{T}\right) & =\sum_{j=1}^{J} w_{j} E_{j}\left[\psi_{j}^{e f f}\left(I_{e f f} \psi_{j}^{e f f}+\Pi\left(S_{\beta} \mid \mathcal{T}_{\eta}\right)\right)^{T}\right] \\
& =\left[\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j}^{e f f} \psi_{j}^{e f f}\right)\right] I_{e f f}+\sum_{j=1}^{J} w_{j} E_{j}\left[\psi_{j}^{e f f} \Pi\left(S_{\beta} \mid \mathcal{T}_{\eta}\right)_{j}^{T}\right] \\
& =I^{k \times k} . \tag{11}
\end{align*}
$$

The last line follows by Theorem 1 since $\Pi\left(S_{\beta} \mid \mathcal{T}_{\eta}\right)$ is perpendicular to $\left[S^{e f f}\right]$. Combining (10) and (11) we get (9).

Very similar arguments applied to $h_{\gamma}$ show that $\left(\psi-\psi^{e f f}, h_{\eta}\right)=0$, so that $\left(\psi-\psi^{\text {eff }}, h\right)=0$. Since $\mathcal{T}$ is the closed linear span of elements such as $h$, it follows that $\psi-\psi^{e f f} \perp \mathcal{T}$.

To prove the second part of the theorem, note that

$$
\begin{aligned}
n \operatorname{Var} \hat{\beta}_{n} & =\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j} \psi_{j}^{T}\right) \\
& =\sum_{j=1}^{J} w_{j} E_{j}\left(\psi_{j}^{e f f} \psi_{j}^{e f f}\right)+\sum_{j=1}^{J} w_{j} E_{j}\left[\left(\psi_{j}-\psi_{j}^{e f f}\right)\left(\psi_{j}-\psi_{j}^{\text {eff }}\right)^{T}\right] \\
& =I_{e f f}^{-1}+\sum_{j=1}^{J} w_{j} E_{j}\left[\left(\psi_{j}-\psi_{j}^{\text {eff }}\right)\left(\psi_{j}-\psi_{j}^{\text {eff }}\right)^{T}\right]
\end{aligned}
$$

The cross product terms vanish by Theorem 1 , since $\psi-\psi^{e f f} \perp \mathcal{T}$ and $\left[\psi^{e f f}\right] \subseteq \mathcal{T}$.

## 3. THE INFORMATION BOUND FOR CASE-CONTROL STUDIES

In this section we apply the theory sketched above in Section 2 to regression models where the data are obtained by case-control sampling. Suppose that we have a response $Y$ (assumed discrete with possible values $\left.y_{1}, \ldots, y_{J}\right)$ and a vector $X$ of covariates, and we want to model the conditional distribution of $Y$ given $X$ using a regression function

$$
f_{j}(x, \beta)=P\left(Y=y_{j} \mid X=x\right)
$$

say, where $\beta$ is a $k$-vector of parameters. If the distribution of the covariates $X$ is specified by a density $\eta$, assumed to be absolutely continuous with respect to a measure $\mu$, then the joint distribution of $X$ and
$Y$ is

$$
f_{j}(x) \eta(x)
$$

and the conditional distribution of $x$ given $Y=y_{j}$ is

$$
p_{j}(x, \beta, \eta)=f_{j}(x, \beta) \eta(x) / \pi_{j}
$$

where

$$
\pi_{j}=\int f_{j}(x, \beta) \eta(x) d \mu(x)
$$

In case-control sampling, the data are not sampled from the joint distribution, but rather are sampled from the conditional distributions of $X$ given $Y=y_{j}$. We are thus in the situation of Section 2 with

$$
p_{j}(x, \beta, \eta)=f_{j}(x, \beta) \eta(x) / \pi_{j} .
$$

To apply the theory of Section 2 , we must identify the spaces $\mathcal{T}, \mathcal{T}_{\beta}$ and $\mathcal{T}_{n}$.
Theorem 4 Let $\mathcal{P}=\left(\mathcal{P}_{1} \times \cdots \times \mathcal{P}_{J}\right)$ with $\mathcal{P}_{j}=\left\{f_{j}(x, \beta) \eta(x) / \pi_{j}: \beta \in B, \eta\right.$ a density $\}$. Then
(i) $\mathcal{T}_{\beta}=\left[S_{\beta}\right]$ where $S_{\beta}=\left(S_{\beta, 1}, \ldots, S_{\beta, J}\right)$, and $S_{\beta, j}=\frac{\partial \log f_{j}(x, \beta)}{\partial \beta}-E_{j}\left[\frac{\partial \log f_{j}(x, \beta)}{\partial \beta}\right]$.
(ii) The nuisance tangent space is $\mathcal{T}_{\eta}=\left\{\left(h-E_{1}(h), \ldots, h-E_{J}(h)\right): h \in L_{2, k}^{0}\left(G_{0}\right)\right\}$, where $d G_{0}=\eta_{0} d \mu$, and $L_{2, k}^{0}\left(G_{0}\right)$ is the space of all $k$-dimensional functions $f$ satisfying $\int\|f\|^{2} \eta_{0}(x) d \mu(x)<\infty$ and $\int f(x) \eta_{0}(x) d \mu(x)=0$.
(iii) The tangent space is $\mathcal{T}=\mathcal{T}_{\beta}+\mathcal{T}_{\eta}$.

Proof. Consider a finite dimensional submodel $\mathcal{Q}$ of $\mathcal{P}$, of the form

$$
\mathcal{Q}_{j}=\left\{p_{j}(x, \gamma)=f_{j}(x, \beta(\gamma)) \eta(x, \gamma) / \pi_{j}: \gamma \in \Gamma\right\}
$$

where $\Gamma$ has dimension $r$, say. The score function for $\mathcal{Q}$ is

$$
\left[\frac{\partial p_{j}(x, \gamma)}{\partial \gamma} p_{j}\right] I_{\left\{p_{j}>0\right\}}
$$

which for simplicity we write as

$$
\frac{\partial \log p_{j}(x, \gamma)}{\partial \gamma}
$$

Direct calculation gives

$$
\frac{\partial \log p_{j}(x, \gamma)}{\partial \gamma}=\frac{\partial \beta}{\partial \gamma}\left[\frac{\partial \log f_{j}(x, \beta)}{\partial \beta}-E_{j}\left(\frac{\partial \log f_{j}(x, \beta)}{\partial \beta}\right)\right]+\frac{\partial \log \eta(x, \gamma)}{\partial \gamma}-E_{j}\left(\frac{\partial \log \eta(x, \gamma)}{\partial \gamma}\right)
$$

so that for a constant matrix $A$ with $k$ rows,

$$
\begin{equation*}
A \frac{\partial \log p_{j}}{\partial \gamma}=A_{1} S_{\beta, j}+A_{2}\left[\frac{\partial \log \eta(x, \gamma)}{\partial \gamma}-E_{j}\left(\frac{\partial \log \eta(x, \gamma)}{\partial \gamma}\right)\right] \tag{12}
\end{equation*}
$$

Now consider the spaces $\mathcal{T}_{\beta}$ and $\mathcal{T}_{\eta}$. To prove (i), note that $\mathcal{T}_{\beta}$ is the closure of the linear span of scores of finite-dimensional submodels of

$$
\mathcal{P}_{\beta}=\left\{\left(p_{1}\left(x, \beta, \eta_{0}\right) \ldots, p_{J}\left(x, \beta, \eta_{0}\right)\right): \beta \in B\right\}
$$

so a calculation similar to (12) shows that $\mathcal{T}_{\beta}=\left[S_{\beta}\right]$.
Now define the operator $T_{r}: L_{2, r}^{0}\left(G_{0}\right) \rightarrow \mathcal{H}$ by

$$
T_{r}(h)=\left(h_{1}-E_{1}\left(h_{1}\right), \ldots, h_{J}-E_{J}\left(h_{J}\right)\right)
$$

Again calculating as in (12), we see that $\mathcal{T}_{\eta}$ is the closure of the linear span, $\mathcal{T}_{\eta}^{0}$ say, of

$$
\bigcup_{r}\left\{T_{r}(h): h \text { is the score of an } r \text {-dimensional submodel of } \mathcal{G}\right\}
$$

where $\mathcal{G}=\{\eta: \eta$ a density for $X\}$. To prove (ii), we must show that

$$
\begin{equation*}
\overline{\mathcal{T}_{\eta}^{0}}=\left\{T_{k}(h): h \in L_{2, k}^{0}\left(G_{0}\right)\right\} \tag{13}
\end{equation*}
$$

Let $h$ be a score of a submodel of $\mathcal{G}$ having dimension $r$, say, and $A$ an $k \times r$ matrix. Then $A T_{r}(h)=T_{k}(A h)$ and $A h$ is in $L_{2, k}^{0}\left(G_{0}\right)$, so that

$$
\begin{equation*}
\mathcal{T}_{\eta}^{0} \subseteq\left\{T_{k}(h): h \in L_{2, k}^{0}\left(G_{0}\right)\right\} \tag{14}
\end{equation*}
$$

Conversely, let $h$ be in $L_{2, k}^{0}\left(G_{0}\right)$. Then using the arguments of Bickel et al. (1993, p 52), it follows that $h$ is the score function of the $k$-dimensional submodel

$$
\left\{\eta_{0}(x)\left(1+\exp \left(-2 \gamma^{T} h(x)\right)^{-1}: \gamma \in \Re_{k}\right\}\right.
$$

so that the reverse inclusion in (14) is also true.
To complete the proof of (13), we show that $\left\{T_{k}(h): h \in L_{2, k}^{0}\left(G_{0}\right)\right\}$ is closed. Let $h_{n}$ be a sequence in $L_{2, k}^{0}\left(G_{0}\right)$ such that $T_{k}\left(h_{n}\right) \rightarrow g$ in $\mathcal{H}$. Note that by definition of the norm in $\mathcal{H}$, we have

$$
\left\|T_{k}\left(h_{n}\right)-g\right\|_{\mathcal{H}}^{2} \geq \frac{w_{j}}{\pi_{j}} \int\left|h_{n}-E_{j}\left(h_{n}\right)-g_{j}\right|^{2} f_{j} d G_{0}
$$

so that $\left(h_{n}-E_{j}\left(h_{n}\right)\right) f_{j}^{1 / 2} \rightarrow g_{j} f_{j}^{1 / 2}$ in $L_{2, k}^{0}\left(G_{0}\right)$, and hence, since the $f_{j}$ 's are bounded, $\left(h_{n}-E_{j}\left(h_{n}\right)\right) b \rightarrow$ $g_{j} b$ in $L_{2, k}^{0}\left(G_{0}\right)$, where $b=\prod_{j=1}^{J} f_{j}^{1 / 2}$. Subtracting, we have $\left(E_{j}\left(h_{n}\right)-E_{J}\left(h_{n}\right)\right) b \rightarrow\left(g_{j}-g_{J}\right) b$ in $L_{2, k}^{0}\left(G_{0}\right)$,
which implies that $E_{j}\left(h_{n}\right)-E_{J}\left(h_{n}\right)$ converges to a constant $c_{j}$ say, and that $\left(g_{j}-g_{J}\right) b=c_{j} b$ a.e. $G_{0}$. Since $b \neq 0, g_{j}=g_{J}+c_{j}$. Moreover, $E_{j}\left(g_{j}\right)=0, j=1, \ldots J$, so that $c_{j}=-E_{j}\left(g_{J}\right)$, and $g=T_{k}\left(g_{J}\right)$. Finally, we show that $g_{j}$ is in $L_{2, k}^{0}\left(G_{0}\right)$. The limit $g_{j} f_{j}^{1 / 2}$ and hence (since the $f_{j}$ 's are bounded) $g_{j} f_{j}$ is in $L_{2, k}^{0}\left(G_{0}\right)$, so

$$
\begin{aligned}
\sum_{j} g_{j} f_{j} & =\sum\left(g_{J}-c_{j}\right) f_{j} \\
& =g_{J}-\sum_{j} c_{j} f_{j} \quad\left(\text { since } \sum_{j} f_{j}=1\right)
\end{aligned}
$$

is also in $L_{2, k}^{0}\left(G_{0}\right)$. Since $\sum_{j} c_{j} f_{j}$ is bounded and hence in $L_{2, k}^{0}\left(G_{0}\right)$, so must be $g_{J}$. Thus $g$ is of the form $T_{k}(h)$ with $h \in L_{2, k}^{0}\left(G_{0}\right)$, which proves (ii).

To prove (iii), let $\mathcal{T}^{0}$ be the linear span of scores of finite-dimensional submodels of $\mathcal{P}$. From (12), we have $\mathcal{T}^{0} \subseteq\left[S_{\beta}\right]+\mathcal{T}_{\eta}^{0}$, and the reverse inclusion is also true since $\left[S_{\beta}\right] \subseteq \mathcal{T}^{0}$ and $\mathcal{T}_{\eta}^{0} \subseteq \mathcal{T}^{0}$. Hence

$$
\begin{aligned}
\mathcal{T} & =\overline{\mathcal{T}^{0}} \\
& =\overline{\left[S_{\beta}\right]+\mathcal{T}_{\eta}^{0}} \\
& =\left[S_{\beta}\right]+\overline{\mathcal{T}_{\eta}^{0}} \quad\left(\text { since }\left[S_{\beta}\right]\right. \text { is finite-dimensional) } \\
& =\mathcal{T}_{\beta}+\mathcal{T}_{\eta} .
\end{aligned}
$$

Our next result derives the efficient score.

Theorem 5 Let $A$ be the operator $L_{2}\left(G_{0}\right) \rightarrow L_{2}\left(G_{0}\right)$ defined by

$$
\begin{equation*}
(A h)(x)=f^{*}(x) h(x)-\sum_{j=1}^{J} \frac{w_{j}}{\pi_{j}} f_{j}(x)\left(f_{j} / \pi_{j}, h\right)_{2} \tag{15}
\end{equation*}
$$

where

$$
f^{*}(x)=\sum_{j=1}^{J} \frac{w_{j}}{\pi_{j}} f_{j}(x)
$$

and $(\cdot, \cdot)_{2}$ is the inner product in $L_{2}\left(G_{0}\right)$. Let $S_{\beta, j}=\left(S_{\beta, j 1}, \ldots, S_{\beta, j k}\right)^{T}$ where $S_{\beta, j l} \in L_{2}\left(G_{0}\right)$, and define $\phi_{l}=\sum_{j=1}^{J} \frac{w_{j}}{\pi_{j}} S_{\beta, j l} f_{j}(x)$. Then the efficient score has $j, l$ element

$$
S_{\beta, j l}-h_{l}^{*}+E_{j}\left[h_{l}^{*}\right]
$$

where $h_{l}^{*}$ is any solution in $L_{2}\left(G_{0}\right)$ of the operator equation

$$
\begin{equation*}
A h_{l}^{*}=\phi_{l} . \tag{16}
\end{equation*}
$$

Proof. The efficient score is the projection of $S_{\beta}$ onto $\mathcal{T}_{\eta}^{\perp}$, so is of the form $S_{\beta}-g$, where $g$ is the unique minimizer of $\left\|S_{\beta}-g\right\|_{\mathcal{H}}^{2}$ in $\mathcal{T}_{\eta}$. By Theorem 4, this is $S_{\beta}-T_{k}\left(h^{*}\right)$, where $h^{*}$ is the (unique) minimizer of $\left\|S_{\beta}-T_{k}(h)\right\|_{\mathcal{H}}^{2}$ in $L_{2, k}^{0}\left(G_{0}\right)$. Write $h^{*}=\left(h_{1}^{*}, \ldots, h_{k}^{*}\right)$. Then

$$
\begin{equation*}
\left\|S_{\beta}-T_{k}\left(h^{*}\right)\right\|_{\mathcal{H}}^{2}=\sum_{l=1}^{k} \sum_{j=1}^{J} \frac{w_{j}}{\pi_{j}} \int\left(S_{\beta, j l}-h_{l}^{*}-E_{j}\left(h_{l}^{*}\right)\right)^{2} f_{j} d G_{0} \tag{17}
\end{equation*}
$$

so that we must choose $h_{l}^{*}$ to minimize

$$
\begin{align*}
\sum_{j=1}^{J} \frac{w_{j}}{\pi_{j}} \int\left(S_{\beta, j l}-h_{l}^{*}-E_{j}\left(h_{l}^{*}\right)\right)^{2} f_{j} d G_{0} & =\sum_{j=1}^{J} w_{j} E_{j}\left(S_{\beta, j l}^{2}\right)+\left(A h_{l}^{*}, h_{l}^{*}\right)_{2}-2\left(\phi_{l}, h_{l}^{*}\right)_{2} \\
& =I_{\beta \beta, l l}+\left(A h_{l}^{*}, h_{l}^{*}\right)_{2}-2\left(\phi_{l}, h_{l}^{*}\right)_{2} \tag{18}
\end{align*}
$$

where $I_{\beta \beta}$ is the information matrix for the parametric part of the model.
Note that (18) is unaltered if we change $h_{l}^{*}$ by constant function. Hence, minimising (18) over $L_{2}^{0}\left(G_{0}\right)$ is the same as minimising over $L_{2}\left(G_{0}\right)$. If $h_{l}^{*}$ in $L_{2}\left(G_{0}\right)$ minimises $(18)$, so does $h_{l}^{*}-E_{0}\left(h_{l}^{*}\right)$ in $L_{2}^{0}\left(G_{0}\right)$, where $E_{0}$ denotes expectation with respect to $G_{0}$.

Now we show that the operator $A$ is self-adjoint and positive semi-definite, in the sense that $(A h, h)_{2} \geq$ 0 . First, for any $h_{1}, h_{2}$ in $L_{2}\left(G_{0}\right)$, we have

$$
\left(h_{1}, A h_{2}\right)_{2}=\int h_{1} h_{2} f^{*} d G_{0}-\sum_{j=1}^{J} w_{j}\left(h_{1}, f_{j} / \pi_{j}\right)_{2}\left(h_{2}, f_{j} / \pi_{j}\right)_{2}
$$

which is symmetric in $h_{1}$ and $h_{2}$. Thus $A$ is self-adjoint.
To demonstrate that $A$ is positive semi-definite, put $S_{\beta, j l}=0$ in (18). Then

$$
(A h, h)=\sum_{j=1}^{J} \frac{w_{j}}{\pi_{j}} \int\left(h-E_{j}(h)\right)^{2} f_{j} d G_{0} \geq 0
$$

Now let $h_{l}^{*}$ be any solution in $L_{2}\left(G_{0}\right)$ to (16). Then for any $h$ in $L_{2}\left(G_{0}\right)$, using the fact that $A$ is self-adjoint,

$$
\begin{aligned}
I_{\beta \beta, l l}+(A h, h)_{2}-2\left(\phi_{l}, h\right)_{2} & =I_{\beta \beta, l l}-\left(A h_{l}^{*}, h_{l}^{*}\right)_{2}+\left(h-h_{l}^{*}, A\left(h-h_{l}^{*}\right)\right)_{2} \\
& \geq I_{\beta \beta, l l}-\left(A h_{l}^{*}, h_{l}^{*}\right)_{2}
\end{aligned}
$$

with equality if $h=h_{l}^{*}$, so that the efficient score has $j, l$ element $S_{\beta, j l}-h_{l}^{*}+E_{j}\left[h_{l}^{*}\right]$ as asserted.
It remains to identify a solution to (16). Define $p_{j}=\frac{w_{j}}{\pi_{j}} f_{j} / f^{*}$ and $v_{j j^{\prime}}=\int p_{j} p_{j^{\prime}} f^{*} d G_{0}$. Let $V=\left(v_{j j^{\prime}}\right)$, $W=\operatorname{diag}\left(w_{1}, \ldots, w_{J}\right)$ and $M=W-V$. Note that the row sums of $M$ are zero, since

$$
w_{j}-\sum_{j^{\prime}=1}^{J} \int p_{j} p_{j^{\prime}} f^{*} d G_{0}=w_{j}-\frac{w_{j}}{\pi_{j}} \int f_{j} d G_{0}=0
$$

Using these definitions and (15), we get

$$
A h_{l}=h_{l} f^{*}-\sum_{j=1}^{J}\left(h_{l}, f_{j} / \pi_{j}\right)_{2} p_{j} f^{*}
$$

so that $A h_{l}=\phi_{l}$ if and only if

$$
h_{l}=\frac{\phi_{l}}{f^{*}}+\sum_{j=1}^{J}\left(h_{l}, f_{j} / \pi_{j}\right)_{2} p_{j} .
$$

This suggests that $h_{l}^{*}$ will be of the form

$$
h_{l}^{*}=\frac{\phi_{l}}{f^{*}}+\sum_{j=1}^{J} c_{j} p_{j}
$$

for some constants $c_{1}, \ldots, c_{J}$. In order that $h_{l}^{*}$ satisfy (16), we must have

$$
f^{*}\left(\frac{\phi_{l}}{f^{*}}+\sum_{j=1}^{J} c_{j} p_{j}\right)-\sum_{j=1}^{J}\left(\frac{\phi_{l}}{f^{*}}+\sum_{j=1}^{J} c_{j} p_{j}, f_{j} / \pi_{j}\right)_{2} p_{j} f^{*}=\phi_{l}
$$

or, equivalently,

$$
\begin{equation*}
\sum_{j=1}^{J}\left\{c_{j}-\sum_{j^{\prime}=1}^{J} c_{j^{\prime}}\left(p_{j^{\prime}}, f_{j} \pi_{j}\right)_{2}-w_{j}^{-1}\left(\phi_{l}, p_{j}\right)_{2}\right\} p_{j} f^{*}=0 \tag{19}
\end{equation*}
$$

Now

$$
\begin{aligned}
\left(p_{j^{\prime}}, f_{j} \pi_{j}\right)_{2} & =\int p_{j^{\prime}}, f_{j} / \pi_{j} d G_{0} \\
& =w_{j}^{-1} \int p_{j^{\prime}}, p_{j} f^{*} d G_{0} \\
& =\left(W^{-1} V\right)_{j j^{\prime}}
\end{aligned}
$$

so that (19) will be satisfied if the vector $c=\left(c_{1}, \ldots, c_{J}\right)^{T}$ satisfies

$$
\begin{equation*}
M c=d_{(l)} \tag{20}
\end{equation*}
$$

where $d_{(l)}=\left(d_{1 l}, \ldots, d_{J l}\right)^{T}$ with $d_{j l}=\left(\phi_{l}, p_{j}\right)_{2}$. Thus we require that $c=M^{-} d_{(l)}$ where $M^{-}$is a generalised inverse of $M$.

Our final result in this section gives the information bound.

Theorem 6 The variance - covariance matrix of the efficient score is $I_{\text {eff }}$ where

$$
\begin{equation*}
I_{e f f, l l^{\prime}}=I_{\beta \beta, l l^{\prime}}-\int \frac{\phi_{l} \phi_{l^{\prime}}}{f^{*}} d G_{0}-d_{(l)}^{T} M^{-} d_{\left(l^{\prime}\right)} \tag{21}
\end{equation*}
$$

Proof.

$$
\begin{aligned}
I_{e f f, l l^{\prime}} & =\sum_{j=1}^{J} \frac{w_{j}}{\pi_{j}} \int\left(S_{\beta, j l}-h_{l}^{*}-E_{j}\left(h_{l}^{*}\right)\right)\left(S_{\beta, j l^{\prime}}-h_{l^{\prime}}^{*}-E_{j}\left(h_{l^{\prime}}^{*}\right)\right) f_{j} d G_{0} \\
& =I_{\beta \beta, l l^{\prime}}+\left(A h_{l}^{*}, h_{l^{\prime}}^{*}\right)_{2}-\left(\phi_{l}, h_{l^{\prime}}^{*}\right)_{2}-\left(\phi_{l^{\prime}}, h_{l}^{*}\right)_{2} \\
& =I_{\beta \beta, l l^{\prime}}-\left(\phi_{l}, h_{l^{\prime}}^{*}\right)_{2} \\
& =I_{\beta \beta, l l^{\prime}}-\int \frac{\phi_{l} \phi_{l^{\prime}}}{f^{*}} d G_{0}-d_{(l)}^{T} M^{-} d_{\left(l^{\prime}\right)}
\end{aligned}
$$

## 4. EFFICIENCY OF THE SCOTT-WILD ESTIMATOR

In a famous paper, Prentice and Pyke (1979) showed that it is possible to estimate odds-ratio parameters from simple case-control studies by using an ordinary prospective regression program. In a series of papers (Scott and Wild 1991, 1997, 2001) Scott and Wild have generalised the classic Prentice-Pyke result to general regression models for a variety of choice-based sampling situations. In this section, we focus on general regression models for case control studies, and show that the Scott-Wild estimators are fully efficient. More general sampling situations will be considered in a forthcoming publication.

Suppose we sample prospectively $n_{1}$ cases and $n_{2}$ controls from their respective populations, and observe covariates $x_{1,1}, \ldots, x_{n_{1}, 1}$ for the cases and $x_{1,2}, \ldots, x_{n_{2}, 2}$ for the controls. Suppose, as in Section 3 , that we have regression functions $f_{j}(x, \beta), j=1,2$, giving the conditional probability that an individual with covariates $x$ is a case $(j=1)$ or a control $(j=2)$. The unconditional distribution $G_{0}$ of the covariates is unspecified. As in Section 3, let $\pi_{1}$ and $\pi_{2}$ be the unconditional probabilities of being a case or control respectively.

Now let $n_{1}$ and $n_{2}$ converge to infinity with $n_{j} /\left(n_{1}+n_{2}\right) \rightarrow w_{j}, j=1,2$, and let $\kappa=\left(w_{1} / \pi_{1}\right) /\left(w_{2} / \pi_{2}\right)$. Put $\theta=(\beta, \kappa)^{T}$ and define $P_{j}^{*}(x, \theta)$ by

$$
\begin{equation*}
\operatorname{logit} P_{j}^{*}(x, \theta)=\operatorname{logit} f_{j}(x, \beta)+\log \kappa \tag{22}
\end{equation*}
$$

Then the Scott-Wild estimator of $\theta$ is the solution of the "pseudo-score" equations

$$
\sum_{j=1}^{2} \sum_{i=1}^{n_{j}} \frac{\partial \log P_{j}^{*}\left(x_{i j}, \theta\right)}{\partial \theta}=0
$$

Scott and Wild show that asymptotic variance of the estimate of $\beta$ is the appropriate block of the inverse of the "pseudo" information matrix

$$
I^{*}(\theta)=\sum_{j=1}^{2} w_{j} E_{j}\left(\left(\frac{\partial \log P_{j}^{*}\left(x_{i j}\right.}{\partial \theta}\right)\left(\frac{\partial \log P_{j}^{*}\left(x_{i j}\right.}{\partial \theta}\right)^{T}\right)
$$

We now demonstrate that the inverse of this block coincides with the information bound in Theorem 6, thus showing that the Scott-Wild estimate is fully efficient. Using the partitioned matrix inverse formula, the inverse of the block is

$$
\begin{equation*}
I^{(1)}-I^{(2)} I^{(2)^{T}} / I^{(3)} \tag{23}
\end{equation*}
$$

where

$$
I^{*}=\left[\begin{array}{rr}
I^{(1)} & \kappa^{-1} I^{(2)} \\
\kappa^{-1} I^{(2)^{T}} & \kappa^{-2} I^{(3)}
\end{array}\right]
$$

Let $S_{j}^{0}$ denote the vector $\frac{\partial \log f_{j}}{\partial \beta}$. Then routine calculations give $P_{j}^{*}(x, \theta)=p_{j}$ and

$$
\begin{aligned}
I^{(1)} & =\int\left(S_{1}^{0}-S_{2}^{0}\right)\left(S_{1}^{0}-S_{2}^{0}\right)^{T} p_{1} p_{2} f^{*} d G_{0} \\
I^{(2)} & =\int\left(S_{1}^{0}-S_{2}^{0}\right) p_{1} p_{2} f^{*} d G_{0} \\
I^{(3)} & =\int p_{1} p_{2} f^{*} d G_{0}
\end{aligned}
$$

Now we evaluate the information bound $I_{\text {eff }}$ using (21) in Section 3. We have

$$
\begin{align*}
I_{\beta \beta, l l^{\prime}} & =\sum_{j=1}^{2} \frac{w_{j}}{\pi_{j}} \int S_{\beta, j l} S_{\beta, j l^{\prime}} f_{j} d G_{0} \\
& =\sum_{j=1}^{2} \int S_{\beta, j l} S_{\beta, j l^{\prime}} p_{j} f^{*} d G_{0} \tag{24}
\end{align*}
$$

and

$$
\frac{\phi_{l}}{f^{*}}=S_{\beta, j l} p_{1}+S_{\beta, 2 l} p_{2}
$$

so that after some algebra we get

$$
\begin{equation*}
I_{\beta \beta, l l^{\prime}}-\int \frac{\phi_{l} \phi_{l^{\prime}}}{f^{*}} d G_{0}=\int\left(S_{\beta, 1 l}-S_{\beta, 2 l}\right)\left(S_{\beta, 1 l^{\prime}}-S_{\beta, 2 l^{\prime}}\right) p_{1} p_{2} f^{*} d G_{0} \tag{25}
\end{equation*}
$$

Now consider the matrix $M$. Since the row sums of $M$ are zero, we can write $M$ as

$$
M=\left[\begin{array}{rr}
I^{(3)} & -I^{(3)} \\
-I^{(3)} & I^{(3)}
\end{array}\right]
$$

so that a generalised inverse of $M$ is

$$
M^{-}=\left[\begin{array}{ll}
1 & 0 \\
0 & 0
\end{array}\right] / I^{(3)}
$$

and $d_{l}^{T} M^{-} d_{l^{\prime}}=d_{1 l} d_{1 l^{\prime}} / I^{(3)}$. Finally, we have $S_{\beta, 1 l}-S_{\beta, 2 l}=\left(S_{1}^{0}-S_{2}^{0}\right)_{l}-K_{l}$ where $K_{l}=\left(E_{1}\left(S_{1}^{0}\right)-\right.$ $\left.E_{2}\left(S_{2}^{0}\right)\right)_{l}$, so that

$$
\begin{align*}
I_{\beta \beta, l l^{\prime}}-\int \frac{\phi_{l} \phi_{l^{\prime}}}{f^{*}} d G_{0} & =\int\left(\left(S_{1}^{0}-S_{2}^{0}\right)_{l}-K_{l}\right)\left(\left(S_{1}^{0}-S_{2}^{0}\right)_{l^{\prime}}-K_{l^{\prime}}\right) p_{1} p_{2} f^{*} d G_{0} \\
& =I_{l l^{\prime}}^{(1)}-K_{l} I_{l^{\prime}}^{(2)}-K_{l^{\prime}} I_{l}^{(2)}+K_{l} K_{l^{\prime}} I^{(3)} \tag{26}
\end{align*}
$$

Moreover, $d_{1 l}=\left(\phi_{l}, p_{1}\right)_{2}=\int\left(S_{\beta, 1 l}-S_{\beta, 1 l}\right) p_{1} p_{2} f^{*} d G_{0}$ so that

$$
\begin{align*}
d_{l}^{T} M^{-} d_{l^{\prime}} & =d_{1 l} d_{1 l^{\prime}} / I_{(3)} \\
& =\int\left(\left(S_{1}^{0}-S 2^{0}\right)_{l}-K_{l}\right) p_{1} p_{2} f^{*} d G_{0} \times \int\left(\left(S_{1}^{0}-S 2^{0}\right)_{l^{\prime}}-K_{l^{\prime}}\right) p_{1} p_{2} f^{*} d G_{0} / I^{(3)} \\
& =\left(I_{l}^{(2)}-K_{l} I^{(3)}\right)\left(I_{l^{\prime}}^{(2)}-K_{l^{\prime}} I^{(3)}\right) / I^{(3)} . \tag{27}
\end{align*}
$$

Substituting (26) and (27) into (21) we see that

$$
I_{e f f, l l^{\prime}}=I_{l l^{\prime}}^{(1)}-I_{l}^{(2)} I_{l^{\prime}}^{(2)} / I^{(3)}
$$

so that the Scott-Wild estimator is fully efficient.

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